



## COURSE SYLLABUS

### **Mechanics 2, 7.5 credits**

*Mekanik 2, 7,5 högskolepoäng*

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<b>Course Code:</b> T2MK10	<b>Education Cycle:</b> First-cycle level
<b>Confirmed by:</b> Dean Dec 1, 2019	<b>Disciplinary domain:</b> Technology
<b>Valid From:</b> Jan 1, 2020	<b>Subject group:</b> MT1
<b>Version:</b> 1	<b>Specialised in:</b> GIF
	<b>Main field of study:</b> Mechanical Engineering

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### **Intended Learning Outcomes (ILO)**

On completion of the course, the student should;

Knowledge and understanding

- have a detailed knowledge of fundamental rigid body dynamics
- show understanding of the fundamental concepts of rigid body dynamics

Skills and abilities

- be able to make free body diagrams of systems of rigid bodies
- be able to develop and solve equations describing motions of rigid bodies
- be able to discuss problems and solutions written and orally.

Judgement and approach

- show ability to select appropriate solution strategies
- show ability to evaluate the plausibility of calculated solutions

### **Contents**

The purpose of the course is to provide knowledge in mechanics.

- Dynamics of particles - repetition
- Systems of particles: Momentum, angular momentum, work, energy
- Rigid body dynamics in 2D: fixed axis rotation, general plane motion, mass moment of inertia, work, energy, impulse, impact
- Rigid body dynamics in 3D: fixed point rotation, kinetic energy, mass moment of inertia tensor, Euler equations, rotation of axis-symmetrical bodies, general three-dimensional motion, imbalance, gyroscopic motion

### **Type of instruction**

Lectures and exercises.

The teaching is conducted in English.

### **Prerequisites**

**Examination and grades**

The course is graded 5,4,3 or Fail.

Registration of examination:

Name of the Test	Value	Grading
Examination <sup>1</sup>	5.5 credits	5/4/3/U
Assingments	2 credits	U/G

<sup>1</sup> Determines the final grade of the course, which is issued only when all course units have been passed.

**Course literature**

Engineering Dynamics SI version 7th edition

J. L. Meriam, L. G. Kraige

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